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La dinámica de sistemas estudia el movimiento considerando las aceleraciones resultantes de la aplicación de fuerzas externas y de la interacción de las fuerzas internas, también conocidas como fuerzas de restricción. Este libro se concentra en el estudio de la dinámica de sistemas asociados con dispositivos robóticos y mecatrónicos, lo que supone una amplia consideración de las leyes de movimiento de Newton y los principios del movimiento rotacional de Euler. Una parte fundamental del libro se concentra en el uso del 'Robotics Toolbox' para Matlab, desarrollado como un entorno para estudiar y simular manipuladores clásicos y robots móviles.

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